

external validation of SBI (against real data, contd.)

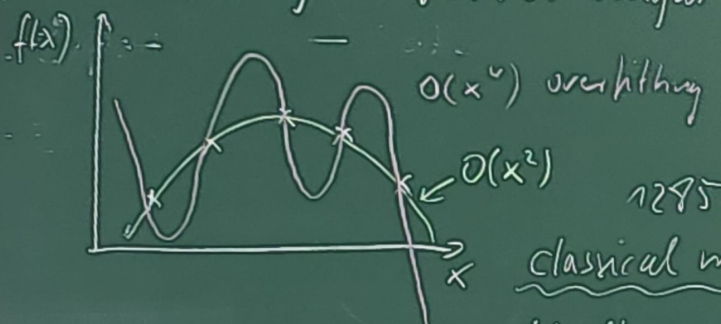
• model misspecification detection: is x^{oss} an outlier to the simulation?
if yes \rightarrow reject x^{oss} and answer "I don't know"

• exploit the feature detection network

- add loss \propto MMD ($p(h(x)) \mid \mathcal{M}(\mathcal{D}, \Pi)$) to pull summary/feature distr. towards standard normal
- reject x^{oss} if $h(x^{oss})$ is an outlier of $\mathcal{M}(\mathcal{D}, \Pi)$

model comparison & selection (between competing theories)

• measuring training error might not be enough, because overfitting might occur



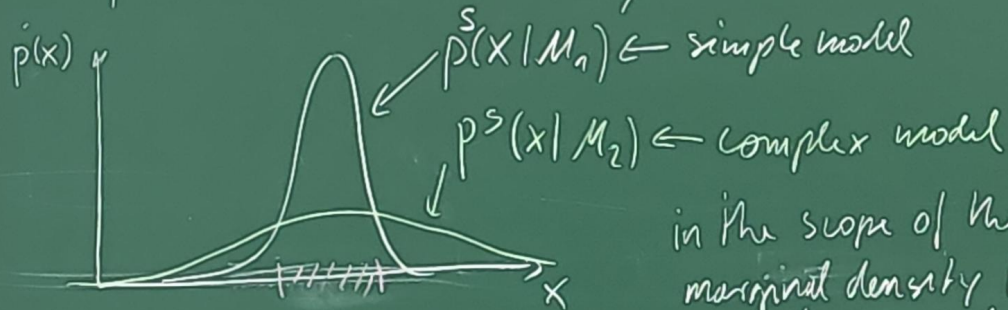
• need trade-off between model accuracy & complexity

(intuition: simpler models generalize better)
1285-1347 "Occam's razor"

classical model selection criteria
Akaïke criterion $AIC = 2 E[NLL] + 2 \text{size}$ (if model param. e.g. # dimensions of linear model)

Bayesian information crit $BIC = 2 \mathbb{E}[NLL] + \log(N)$ size \uparrow dataset size

• in Bayesian inference, model complexity is penalized automatically



M_1, \dots, M_L competing simulations

in the scope of the simple model ~~|||||~~, the marginal density for M_1 is much higher than for M_2 due to normalization of probs

\Rightarrow if $x^{obs} \in \text{|||||}$, during training of SBI, it typically came from $M_1 \Rightarrow$ automatically prefer M_1 during inference as well noise outsourcing

forward model

$$\underbrace{p(M)}_{\text{num } p(M, L)} \cdot p(Y|M) \cdot \underbrace{p(\eta|M, Y) \cdot \delta(X - \Phi_M(Y, \eta))}_{\substack{\text{simulation } M \\ \text{likelihood}}} = p(X|Y, M)$$

marginal density

$$p(x|M) = \int p(x|y, M) p(y|M) dy$$

⇒ model comparison (1): Bayes factor = $\frac{p(x=x^{obs} | M_e)}{p(x=x^{obs} | M_c)}$ $\left\{ \begin{array}{l} > 1 \text{ prefer } M_e \\ < 1 \text{ prefer } M_c \end{array} \right.$

posterior for model preferences

$$p(M|X) = \frac{p(x|M) p(M)}{p(x)}$$

$$p(x) = \sum_{e=1}^L p(M=e) p(x|M=e)$$

⇒ model comparison (2): posterior odds $\frac{p(M_e | x=x^{obs})}{p(M_c | x=x^{obs})}$

equal to Bayes factor if $p(M) = \text{uniform}(1, L)$

practical alg.: train a standard softmax classifier for $p(M|X)$

• comparison thresholds

$$\frac{p(M_e | x^{obs})}{p(M_c | x^{obs})} = r$$

- $\frac{1}{3} < r < 3$: no significant differences
- $3 < r < 10$: substantial evidence for M_e
- $10 < r < \frac{30}{100}$: strong —||—
- $\frac{30}{100} < r$: overwhelming —||—
- otherwise $\frac{1}{30}, \frac{1}{10}, \frac{1}{3}$: evidence for M_c

external validation alg.

given competing theories M_1, \dots, M_L

[epidemiology: different # compartments, priors, observation uncertainty etc]

(1) create synthetic training data

$$TS_e = \left\{ \left(Y_{ei} \sim p(Y|M=e), X_i \sim p(X|Y_{ei}, M=e) \right) \right\}_{i=1}^{N_e} \quad TS = \{ TS_1, \dots, TS_L \}$$

(2) train a separate SBI model for each TS_e with MMD, so that $p(h_e(x)) = N(0, \Sigma)$

(3) perform internal validation for each e , redesign SBI_e until successful

(4) train a softmax classifier $p(M|X)$ using combined TS

$$\hat{p}(M|X) = \underset{p}{\operatorname{arg\,min}} \quad \frac{1}{L} \sum_{e=1}^L \frac{1}{N_e} \sum_{i=1}^{N_e} -\log p(M=e|X=X_{ie}) \quad \text{cross-entropy loss}$$

(5) external validation given X^{obs}

(a) model misspecification detection: $M^{in} = \{ l : h_e(X^{obs}) \text{ is outlier of } N(0, \Sigma) \}$

(b) compute logits of model classifier s_e (penultimate layer, before softmax)

(c) define classifier $p(M|X^{obs}) = \operatorname{softmax}(s_e : l \in M^{in})$

(d) model comparison by posterior odds

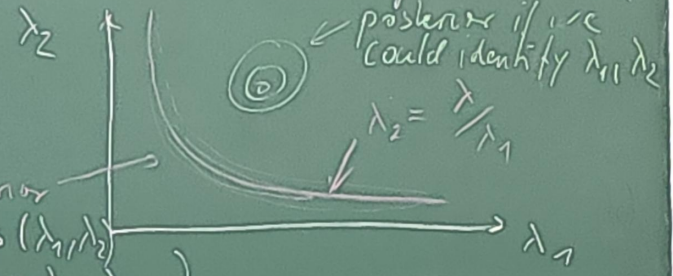
parameter degeneracy

- sometimes, some elements in Y cannot be fully identified from X
 - correlations in the posteriors

example - epidemiologist write SIR equations in terms of natural / conceptual parameters

- λ_1 - average number of people a healthy person meets per day
- λ_2 - fraction of dangerous meetings leading to transmission
- in SIR eq., we always have $\lambda_1 \cdot \lambda_2$ \Rightarrow we cannot distinguish them
- but, we can infer $\lambda = \lambda_1 \cdot \lambda_2$

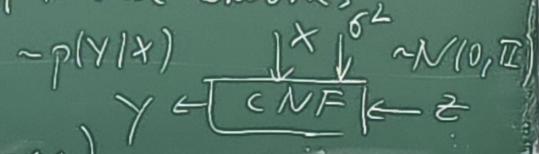
\Rightarrow if we still use λ_1 & $\lambda_2 \Rightarrow$ posterior shows the dependency



actual posterior
(infinitely many pairs (λ_1, λ_2) for fixed $\lambda = \lambda_1 \cdot \lambda_2$)

here, cause of degeneracy is easy to spot, but generally difficult and hard to distinguish from bad convergence of neural networks

- CNF struggle when $p(Y|X)$ is degenerate, because
 - code distribution $N(0, \Sigma)$ has D dimensions
 - but $p(Y|X)$ has $< D$ dimensions ($\hat{=}$ degeneracy)



Theorem: Bijective transformations are only possible if dimension does not change
e.g. NF

• trick to learn a good approximation Soft Flow [Kumar et al. 2020]

- idea: add noise to Y_i from TS to make it D-dimensional

D-dimension Gaussian $N(0, \sigma^2 I)$

- vary σ^2 during training according to $\sigma^2 \sim p(\sigma^2)$

- tell NF about current value of σ^2 (additional condition $p(Y|X, \sigma^2)$)

→ network learns to generate data with given amount of noise σ^2

- at inference time, make $\sigma^2 \rightarrow \sigma_{\min}^2$ (σ_{\min}^2 smallest prior value during training)

→ line $\lambda_2 = \lambda_1 / \lambda_2$ becomes as narrow as possible

(ideally, do inference $\sigma^2 \rightarrow 0$, but practical NF saturate at some limit σ_{\min}^2)

[do not confuse with Noise Net adds noise to X
Soft Flow — " — Y]

