

Robotics 2020/21

I lecture

What is a matrix?

A matrix $m \times n$ is a table of $m \cdot n$ elements ordered in m rows and n columns

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

- If: - $m \neq n \Rightarrow$ rectangular matrix
- $m = n \Rightarrow$ squared matrix
- $m = 1 \vee n = 1 \Rightarrow$ vector

What is the transpose of a matrix?

Given A matrix A^T is the matrix obtained swapping in order the rows and the columns of A.

EX.

$$A = \begin{pmatrix} 2 & 3 \\ 1 & 0 \\ 5 & \pi \end{pmatrix} \Rightarrow A^T = \begin{pmatrix} 2 & 1 & 5 \\ 3 & 0 & \pi \end{pmatrix}$$

Basic operations:

- SUM \forall only if they have same dimensions $m \times n$

$$A + B = C \Rightarrow a_{ij} + b_{ij} = c_{ij}$$

- PRODUCT with a scalar

$$\lambda A = (\lambda a_{ij}) \forall i, j$$

- PRODUCT between matrices
ROWS X COLUMNS

$$A = \begin{pmatrix} 1 & 2 & 4 \\ 0 & 3 & 2 \end{pmatrix} \quad B = \begin{pmatrix} 0 & 3 \\ 1 & 2 \\ 0 & 0 \end{pmatrix} \Rightarrow A \cdot B = \begin{pmatrix} 2 & 7 \\ 3 & 6 \end{pmatrix}$$

! $A \cdot B \neq B \cdot A$ ORDER IS IMPORTANT

$$B \cdot A = \begin{pmatrix} 0 & 9 & 6 \\ 1 & 8 & 8 \\ 0 & 0 & 0 \end{pmatrix}$$

What is an ORTHOGONAL matrix?

A is orthogonal if $A \cdot A^T = I$ with $I = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & 0 & \dots & 1 \end{pmatrix}$

$$\Rightarrow A^T = A^{-1}; \det(A) = 1 \vee -1$$

if A orthogonal and B orthogonal $\Rightarrow C = A \cdot B$ is also

Inverse of a matrix A^{-1} or A^{-1}

What is the determinant of a matrix?

$\det(A)$ is a number that associates important properties of a matrix.

Given a square matrix $A_{n \times n} \Rightarrow$

• if $n = 1 \Rightarrow \det(A) = a_{11}$

• if $n = 2 \Rightarrow \det(A) = a_{11} \cdot a_{22} - a_{12} \cdot a_{21}$

• if $n = 3 \Rightarrow \det(A) = a_{11}(a_{22} \cdot a_{33} - a_{23} \cdot a_{32}) - a_{12}(a_{21} \cdot a_{33} - a_{23} \cdot a_{31}) + a_{13}(a_{21} \cdot a_{32} - a_{22} \cdot a_{31})$

EX.

$$A = \begin{pmatrix} 1 & 0 & 5 \\ 2 & -1 & 0 \\ 7 & -2 & 0 \end{pmatrix}$$

$$\Rightarrow \det(A) = 1(0-0) - 0(\dots) + 5(-4+7) = 15$$

Inverse of a matrix

$$A = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$$

① $\det(A) \neq 0$

$$\det(A) = 2 - 1 = 1 \text{ ok!}$$

\Rightarrow we can invert

② $A^{-1} = \frac{1}{\det(A)} \text{Adj}(A)$ with $\text{Adj}(A) = \begin{pmatrix} \text{Cof}(a_{11}) & \text{Cof}(a_{12}) \\ \text{Cof}(a_{21}) & \text{Cof}(a_{22}) \end{pmatrix}^T$

$\text{Cof}(a_{ij}) = (-1)^{i+j} \cdot \det(A_{ij})$ with A_{ij} the sub-matrix without i -row and j -column

$$\text{Cof}(a_{11}) = (-1)^{1+1} \det(2) = 2$$

$$\dots \Rightarrow \text{Adj}(A) = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}^T = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$\frac{1}{\det(A)} = 1 \Rightarrow A^{-1} = 1 \cdot \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

Rank of a matrix

max number of rows/columns linearly independent

How can we check that?

$$A = \begin{pmatrix} 1 & -1 & 2 \\ 2 & 3 & 4 \\ 3 & 2 & 6 \end{pmatrix}$$

$$\det(A) = 1(18-8) + 1(12-12) + 2(4-9) = 10 - 10 = 0$$

$\det(A) = 0 \Rightarrow$ check sub-matrices

$$A \begin{pmatrix} 1 & -1 & 2 \\ 2 & 3 & 4 \\ 3 & 2 & 6 \end{pmatrix} \rightarrow \det \begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix} = 3 + 2 = 5 \Rightarrow \neq 0$$

$$\text{rk}(A) = 2$$

Last point

PRODUCT BETWEEN VECTORS

Let's consider 2 vectors: $\vec{v} = (v_1, v_2, v_3)$ and $\vec{w} = (w_1, w_2, w_3)$
and let's call the vectors $(\vec{i}, \vec{j}, \vec{k})$

$$\Rightarrow \vec{v} \times \vec{w} = (v_2 w_3 - v_3 w_2) \vec{i} + (v_3 w_1 - v_1 w_3) \vec{j} + (v_1 w_2 - v_2 w_1) \vec{k}$$

how to remember? $\vec{v} \times \vec{w} =$

$$\begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{pmatrix} = v_2 w_3 \vec{i} + v_3 w_1 \vec{j} + v_1 w_2 \vec{k} - w_1 v_2 \vec{k} - w_3 v_1 \vec{j} - w_2 v_3 \vec{i}$$
$$\vec{i} (v_2 w_3 - v_3 w_2) - \vec{j} (v_1 w_3 - v_3 w_1) + \vec{k} (v_1 w_2 - v_2 w_1)$$